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#include <msp430g2211.h>

#define Reed1Mask 0b10000000;
#define Reed2Mask 0b10000000;

/*SLED is now active high in the latest implementation, 1 means segment is on */
#define NeutralMask 0b01101101;
#define Gear1Mask 0b01000100;
#define Gear2Mask 0b01111010;
#define Gear3Mask 0b01011110;
#define Gear4Mask 0b01000111;
#define Gear5Mask 0b00011111;
#define Gear6Mask 0b00111111;
#define ErrorMask 0b00111011;

#define ALLMask 0b01111111; //used to turning off the port each time

/* very gay, but im sure Adam will love this...plus it sort of tests the LEDs at turn on */
#define A 0b01101111;
#define Line 0b00000010;
#define F 0b00101011;
#define U 0b01110101;
#define G 0b00111111;
#define E 0b00111011;

int state = 0;

int main(void) {
    /*Hold the watchdog timer */
    WDTCTL = WDTPW + WDTHOLD;

    //7 Seg setup
    P1SEL = 0; // I/o function
    P2SEL &= ~Reed2Mask; //Set low to ignore the Xtal input
    P1DIR = 0x7f; //Set bits 0-6 to outputs
    P1OUT &= ~0x7f; //Turn all the LED's off

    //Reed Setup
    P1DIR &= ~Reed1Mask; //Insure that bit7 is set low (input)
    P2DIR &= ~Reed2Mask; //Insure that bit7 is set low (input)
    P1OUT |= Reed1Mask; //Pull High
    P2OUT |= Reed2Mask; //Pull High
    P1REN |= Reed1Mask; //Internal Pullup
    P2REN |= Reed2Mask; //Internal Pullup
    P1IES |= Reed1Mask; //High>Low Transition
    P2IES |= Reed2Mask; //High>Low Transition
    P1IFG &= ~Reed1Mask; //clear
    P2IFG &= ~Reed2Mask; //clear
    P1IE |= Reed1Mask; //Enable interrupts on Reed1
    P2IE |= Reed2Mask; //Enable interrupts on Reed2

    _BIS_SR(GIE); //Enable Global Interrupts

    //LED test
    P1OUT &= ~ALLMask; //turns off all the LEDs
    P1OUT |= A; //Puts an A on the screen by only turning on the A mask.
    volatile int j = 0;
    for(j=0; j<20000; j++);
    P1OUT &= ~ALLMask;
    P1OUT |= Line;
    for(j=0; j<20000; j++);
    P1OUT &= ~ALLMask;
    P1OUT |= F;
    for(j=0; j<20000; j++);
    P1OUT &= ~ALLMask;
    P1OUT |= U;
    for(j=0; j<20000; j++);
    P1OUT &= ~ALLMask;
    P1OUT |= G;
    for(j=0; j<20000; j++);
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P1OUT &= ~ALLMask;
P1OUT |= E;
for(j=0; j<20000; j++);

while (1){

    //state machine here
    switch(state) {
        case 0:
            P1OUT &= ~ALLMask;
            P1OUT |= NeutralMask;
            break;
        case 1:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear1Mask;
            break;
        case 2:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear2Mask;
            break;
        case 3:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear3Mask;
            break;
        case 4:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear4Mask;
            break;
        case 5:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear5Mask;
            break;
        case 6:
            P1OUT &= ~ALLMask;
            P1OUT |= Gear6Mask;
            break;
        default:
            P1OUT &= ~ALLMask;
            P1OUT |= ErrorMask; //Error state, hopefully won't end up here!
            break;
    }
}

//ISRs
void Port_1(void) __attribute__((interrupt(PORT1_VECTOR)));
void Port_1(void)
{
    P1IFG &= ~Reed1Mask; //Clear the interuupt
    P1IE &= ~Reed1Mask; //Disable Interrupts to handle button bounce
    // set the watchdog timer to trigger every 32
    WDTCTL = WDT_MDLY_32;
    // clear Watchdog INT flag
    IFG1 &= ~WDTIFG;
    // enable watchdog timer interrupts; in .... the button will be re-enabled
    // by WDT_IST() --program can still run
    IE1 |= WDTIE;
}

void Port_2(void) __attribute__((interrupt(PORT2_VECTOR)));
void Port_2(void)
{
    P2IFG &= ~Reed2Mask; //Clear the interuupt
    P2IE &= ~Reed2Mask; //Disable Interrupts to handle button bounce
    // set the watchdog timer to trigger every 32ms
    WDTCTL = WDT_MDLY_32;
    // clear Watchdog INT flag
    IFG1 &= ~WDTIFG;
    // enable watchdog timer interrupts; in .... the button will be re-enabled
    // by WDT_IST() --program can still run
    IE1 |= WDTIE;
}

void WDT_ISR() __attribute__((interrupt(WDT_VECTOR)));
void WDT_ISR(void)

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```
{
// Disable interrupts on the watchdog timer
IE1 &= ~WDTIE;
// clear the interrupt flag for the watchdog timer
IFG1 &= ~WDTIFG;
// resume holding the watchdog timer so it doesn't reset the chip
WDTCTL = WDTPW + WDTHOLD;
//after the set time check the input again and if it is still high then we have a debounced button
//if (state<6 & (!P1IN & Reed1Mask)) state++; //increments the state, if its not over 6, and the
button is still pressed.
    volatile int i = 0;
    for(i=0; i<500; i++); //crappy adjustable delay, shouldn't be needed but the wdt delay is
ruined by not having an external clock (32ms max)

    if((P1IN & 0b10000000) == 0){
        if(state<6) state++; //increments the state, if its not over 6, and the button
is still pressed.
    }
    else if((P2IN & 0b10000000) == 0){
        if(state>0) state--; //decrements the state, if its over 0, and the button is
still pressed.
    }

// re-enable interrupts on the button
P1IFG &= ~Reed1Mask; //clear any interrupts before re enable
P1IE |= Reed1Mask;
P2IFG &= ~Reed2Mask; //clear any interrupts before re enable
P2IE |= Reed2Mask;
}
```